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INFORMATION DISCLOSURE STATEMENT BY APPLICANT

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First Named Inventor	Jun HAGIHARA
Art Unit	3664
Examiner Name	Spencer D PATTON
Attorney Docket Number	Q87381

U.S. PATENTS						
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	1					

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FOREIGN PATENT DOCUMENTS								
Examiner Initials*	Cite No	Foreign Document Number ³	Country Code ²	Kind Code⁴	Publication Date	Name of Patentee or Applicant of cited Document	Pages, Columns, Lines, Where Relevant Passages or Relevant Figures Appear	T⁵
/S.P./	1	05-143106	JP	Α	1993-06-11	Nikon Corp.		Abstract

NON-PATENT LITERATURE DOCUMENTS					
Examiner Initials*	Cite No	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city, and/or country where published.	T⁵		
/S.P./	1	Supplemental European Search Report for Application No. 03736051.8-1239/1550924, dated March 8, 2010.	Υ		
/S.P./	2	Michael THUMMEL, et al.; "Control of Robots with Elastic Joints based on Automatic Generation of Inverse Dynamics Models"; Proceedings of the 2001 IEEE/RSI Int'l conference on Intelligent Robots and Systems; October 29 - Nov 3, 2001; Vol. 2, pages 925 - 930; XP010571815; ISBN: 978-0-7803-6612-1	Υ		
/S.P./	3	Hendrik VAN BRUSSEL, et al.; "Accurate Motion Controller Design Based on an Extended Pole Placement Method and Disturbance Observer"; CIRP ANNALS - Manufacturing Technology; Int. Inst. For Production Engineering Research; 1994; Vol. 43 No. 1, pages 367-375; XP002570457	Y		

EXAMINER SIGNATURE					
Examiner Signature	/Spencer Patton/	Date Considered	08/04/2010		

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